

# Model Averaging (Bayesian Learning)

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- What assumptions are made here?

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- $P(E_s)$  is a normalizing constant so the probabilities of the models sum to 1.
- You could try to fit the training data as well as possible by picking the **maximum likelihood model**, but that overfits.

# Independent and Identically Distributed

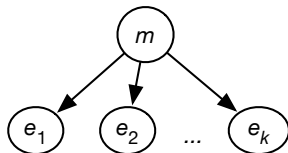
- Examples  $E_s = [e_1, \dots, e_k]$  are **independent and identically distributed (i.i.d.)** given model  $m$  if

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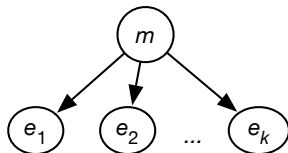
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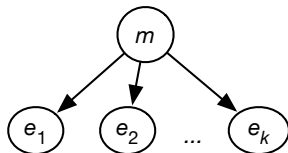


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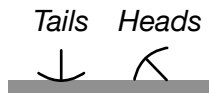
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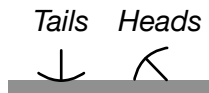
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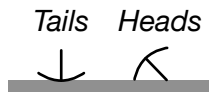
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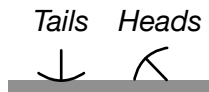
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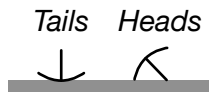
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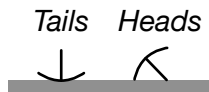
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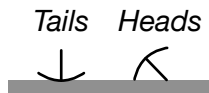
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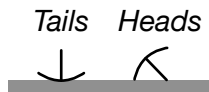
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— empirical frequency overfits to the data.

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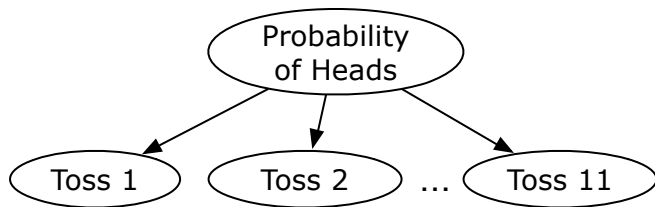
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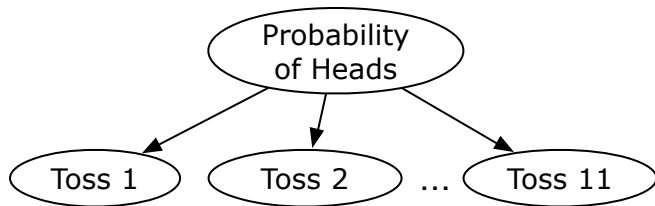
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- Which restaurants have a rating of 5?
  - ▶ Only restaurants with few ratings have an average rating of 5.
- Solution: add some “average” ratings for each restaurant!



[aipython.org](http://aipython.org): coinTossBN in learnBayesian.py

- *Probability\_of\_Heads* is a random variable representing the probability of heads.
- Domain is  $\{0.0, 0.1, 0.2, \dots, 0.9, 1.0\}$  or interval  $[0, 1]$ .
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- *Toss#i* is independent of *Toss#j* (for  $i \neq j$ ) given *Probability\_of\_Heads*
- **i.i.d.** or **independent and identically distributed**.

# Bayesian Learning of Probabilities

- $Y$  has two outcomes  $y$  and  $\neg y$ .  
We want the probability of  $y$  given training examples  $E_s$ .
- Treat the probability of  $y$  as a real-valued random variable on the interval  $[0, 1]$ , called  $\phi$ . Bayes' rule gives:

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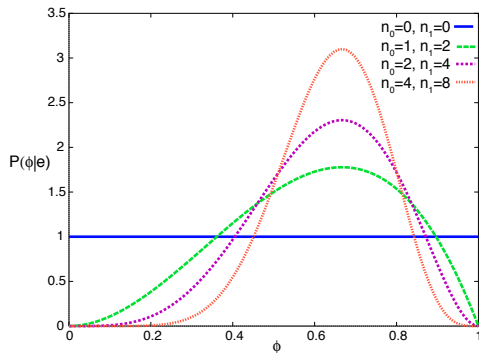
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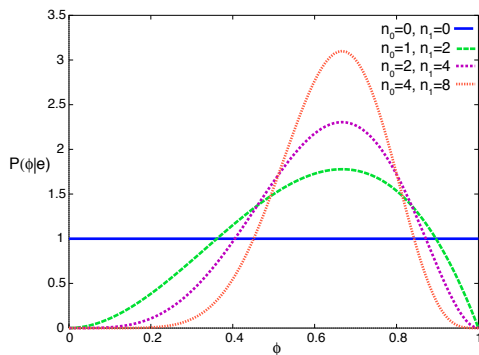
- Uniform prior:  $P(\phi=p) = 1$  for all  $p \in [0, 1]$ .

# Posterior Probabilities for Different Training Examples (beta distribution)



AIPython.org see probBeta.py

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- The mode is the empirical average.
- The expected value is Laplace smoothing (pseudo-count of 1).

$$\text{Beta}^{\alpha_0, \alpha_1}(p) = \frac{1}{K} p^{\alpha_1-1} \times (1-p)^{\alpha_0-1}$$

where  $K$  is a normalizing constant.  $\alpha_i > 0$ .

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- If the prior is of the form of a beta distribution, so is the posterior — called a **conjugate distribution**.

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- A **Dirichlet distribution** has form:

$$\text{Dirichlet}^{\alpha_1, \dots, \alpha_k}(p_1, \dots, p_k) = \frac{\prod_{j=1}^k p_j^{\alpha_j - 1}}{Z}$$

where

- ▶  $p_i$  is the probability of the  $i$ th outcome (and so  $0 \leq p_i \leq 1$ )
- ▶  $\alpha_i$  is a positive real number (a “count”)
- ▶  $Z$  is a normalizing constant that ensures the integral over all the probability values is 1.

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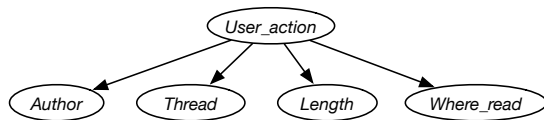
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- the numbers from different experts can be added
- the number can be combined with real data
- the effective sample size ( $m$ ) can be tuned to reflect expertise.

# Probabilistic Classifiers

- A **Bayes classifier** is a probabilistic model that is used for supervised learning.
- idea: the role of a **class** is to predict the values of features for members of that class.
- In a **naive Bayes classifier** the input features are conditionally independent of each other given the classification.  
Example: Suppose an agent wants to predict the user action based on properties of an online discussion:



# Naive Bayes Classifiers

With inputs  $X_1=v_1, \dots, X_k=v_k$ , and classification,  $Y$ :

$$\begin{aligned} & P(y \mid X_1=v_1, \dots, X_k=v_k) \\ &= \frac{P(y) * \prod_{i=1}^k P(X_i=v_i \mid y)}{P(y) * \prod_{i=1}^k P(X_i=v_i \mid y) + P(\neg y) * \prod_{i=1}^k P(X_i=v_i \mid \neg y)} \\ &= \frac{1}{1 + \frac{P(\neg y) * \prod_{i=1}^k P(X_i=v_i \mid \neg y)}{P(y) * \prod_{i=1}^k P(X_i=v_i \mid y)}} \\ &= \frac{1}{1 - \exp(\log(\frac{P(\neg y) * \prod_{i=1}^k P(X_i=v_i \mid \neg y)}{P(y) * \prod_{i=1}^k P(X_i=v_i \mid y)})})} \\ &= \textit{sigmoid} \left( \log\left(\frac{P(y)}{P(\neg y)}\right) + \sum_i \log\left(\frac{P(X_i=v_i \mid y)}{P(X_i=v_i \mid \neg y)}\right) \right) \end{aligned}$$

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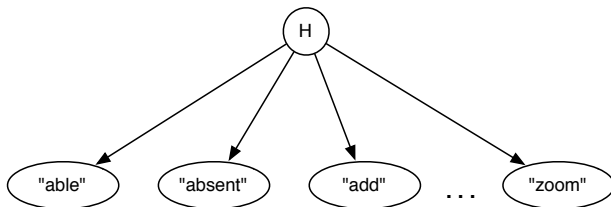
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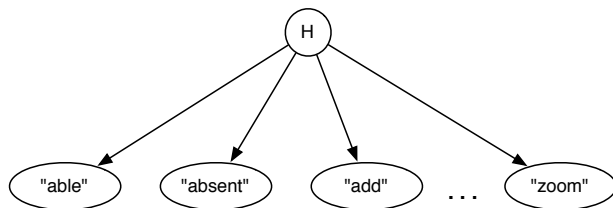
is a Logistic regression model when all  $X_j$  are observed

# Naive Bayes Classifier: User's request for help



$H$  is the help page the user is interested in.  
We observe the words in the query.

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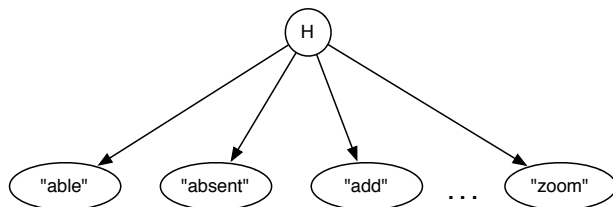


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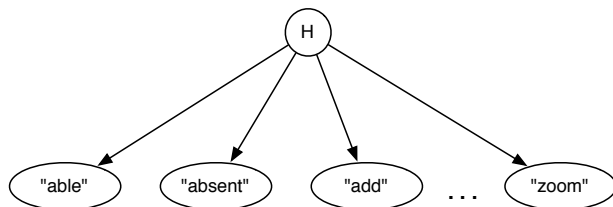
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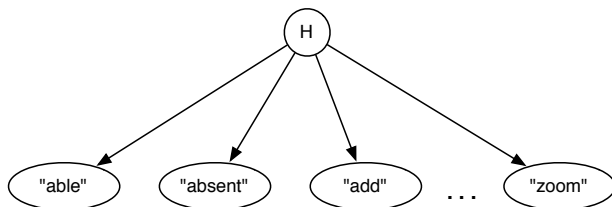
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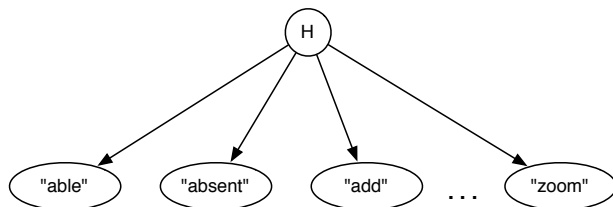
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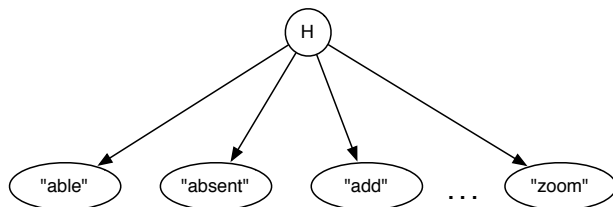
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What prior counts should be used? Can they be zero?



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- Maintain “counts” (pseudo counts + observed cases):
  - ▶  $c_i$  the number of times  $h_i$  was the correct help page
  - ▶  $s = \sum_i c_i$
  - ▶  $u_{ij}$  the number of times  $h_i$  was the correct help page and word  $w_j$  was used in the query.
- $P(h_i) = c_i/s$
- $P(w_j | h_i) = u_{ij}/c_i$

- $Q$  is the set of words in the query.
- Learning: if  $h_i$  is the correct page: Increment  $s$ ,  $c_i$  and  $u_{ij}$  for each  $w_j \in Q$ .
- Inference:

$$P(h_i | Q) \propto P(h_i) \prod_{w_j \in Q} P(w_j | h_i) \prod_{w_j \notin Q} (1 - P(w_j | h_i))$$

*expensive*  
*inference*  $\rangle$   $= \frac{c_i}{s} \prod_{w_j \in Q} \frac{u_{ij}}{c_i} \prod_{w_j \notin Q} \frac{c_i - u_{ij}}{c_i}$

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 &= \frac{c_i}{s} \prod_{w_j} \frac{c_i - u_{ij}}{c_i} \prod_{w_j \in Q} \frac{u_{ij}}{c_i - u_{ij}} \\
 \left. \begin{array}{l} \text{expensive} \\ \text{learning} \end{array} \right\} &= \psi_i \prod_{w_j \in Q} \frac{u_{ij}}{c_i - u_{ij}}
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- What do we do with new help pages?
- How can we transfer the language model to a new help system?