

# Learning a Belief Network

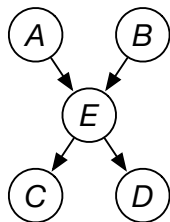
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# Learning a Belief Network

- If you
    - ▶ know the structure
    - ▶ have observed all of the variables
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  - you can learn each conditional probability separately.
- supervised learning

# Learning belief network example

Model



Data

<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
<i>t</i>	<i>f</i>	<i>t</i>	<i>t</i>	<i>f</i>
<i>f</i>	<i>t</i>	<i>t</i>	<i>t</i>	<i>t</i>
<i>t</i>	<i>t</i>	<i>f</i>	<i>t</i>	<i>f</i>
		...		

→ Probabilities

$P(A)$   
 $P(B)$   
 $P(E | A, B)$   
 $P(C | E)$   
 $P(D | E)$

- Each conditional probability distribution can be learned separately:
- For example:

$$P(E = t \mid A = t \wedge B = f) \\ = \frac{(\# \text{examples: } E = t \wedge A = t \wedge B = f) + c_1}{(\# \text{examples: } A = t \wedge B = f) + c}$$

where  $c_1$  and  $c$  reflect prior (expert) knowledge ( $c_1 \leq c$ ).

- When there are many parents to a node, there can be little or no data for each conditional probability:

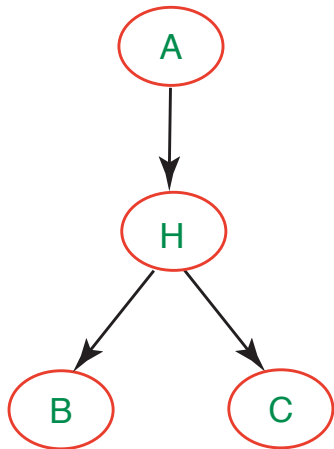
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where  $c_1$  and  $c$  reflect prior (expert) knowledge ( $c_1 \leq c$ ).

- When there are many parents to a node, there can be little or no data for each conditional probability: use supervised learning to learn a decision tree, linear classifier, a neural network or other representation of the conditional probability.

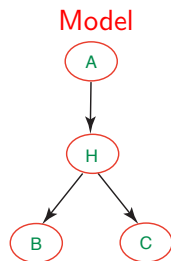
# Unobserved Variables



- What if you had only observed values for A, B, C?

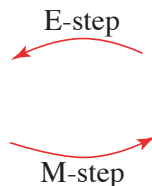
A	B	C
<i>t</i>	<i>f</i>	<i>t</i>
<i>f</i>	<i>t</i>	<i>t</i>
<i>t</i>	<i>t</i>	<i>f</i>
...		

# EM Algorithm



Augmented Data

<i>A</i>	<i>B</i>	<i>C</i>	<i>H</i>	<i>Count</i>
<i>t</i>	<i>f</i>	<i>t</i>	<i>t</i>	0.7
<i>t</i>	<i>f</i>	<i>t</i>	<i>f</i>	0.3
<i>f</i>	<i>t</i>	<i>t</i>	<i>f</i>	0.9
<i>f</i>	<i>t</i>	<i>t</i>	<i>t</i>	0.1
	...			...



Probabilities

$$P(A)$$
$$P(H | A)$$
$$P(B | H)$$
$$P(C | H)$$

- Repeat the following two steps:
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- Start either with made-up data or made-up probabilities.
- EM will converge to a local maxima.

# Belief network structure learning (I)

Given examples  $\mathbf{e}$ , and model  $m$ :

$$P(m | \mathbf{e}) = \frac{P(\mathbf{e} | m) * P(m)}{P(\mathbf{e})}.$$

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- Taking logarithms (and negating):

$$\arg \max_m P(m | \mathbf{e}) = \arg \min_m (-\log P(\mathbf{e} | m) - \log P(m))$$



Bayes Rule:

$$P(h|d) \propto P(d|h)P(h)$$

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- $\log P(d|h)$  measures fit to data
- $\log P(h)$  measures model complexity

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- Can you do better?

Consider a code to distinguish elements of  $\{a, b, c, d\}$  with

$$P(a) = \frac{1}{2}, P(b) = \frac{1}{4}, P(c) = \frac{1}{8}, P(d) = \frac{1}{8}$$

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The code 0111110010100 represents string *adcabba*

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- The expected number of bits it takes to describe a distribution given evidence  $e$ :

$$I(e) = \sum_x -P(x|e) * \log_2 P(x|e).$$



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- When is this large? When  $P(x) \gg Q(x)$  for some  $x$ .



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  - ▶ How to determine  $-\log P(m)$ ?

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- If there are  $||m||$  independent parameters ( $||m||$  is the dimensionality of the model):

$$-\log P(m | \mathbf{e}) \propto -\log P(\mathbf{e} | m) + ||m|| \log(|\mathbf{e}|)$$

This is the **Bayesian Information Criterion (BIC)** score.

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## Belief network structure learning (II)

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- Search over total orderings of variables



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- In general you need to model why data is missing (see Chapter 11)

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- We are not given the structure.
- We don't know whether there are hidden variables or not. We don't know the domain size of hidden variables.
- There is missing data.

... this is too difficult for current techniques!